

SP100B

VERSATILE, 7-AXIS ROBOT

KEY BENEFITS

Single robot-to-controller cable connection enables fast setup

High-speed robot motion reduces air-cut time for spot gun

7-axis design provides expanded effective motion range

SPECIFICATIONS

100 kg payload with spot harness

110 kg payload without spot harness

2,236 mm horizontal reach

3,792 mm vertical reach

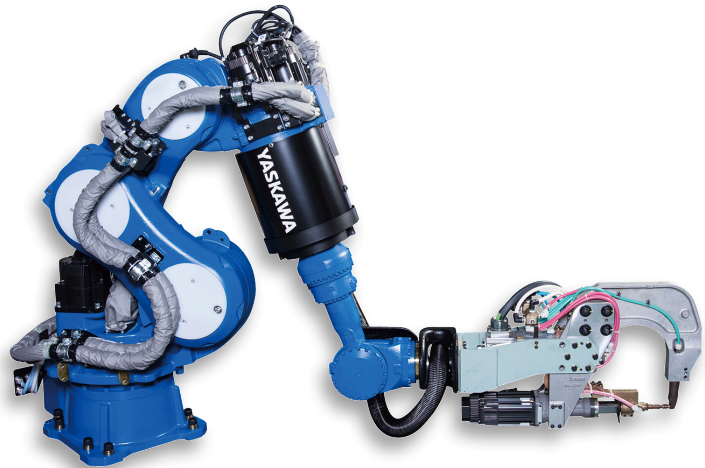
0.04 mm repeatability

APPLICATION

Spot Welding

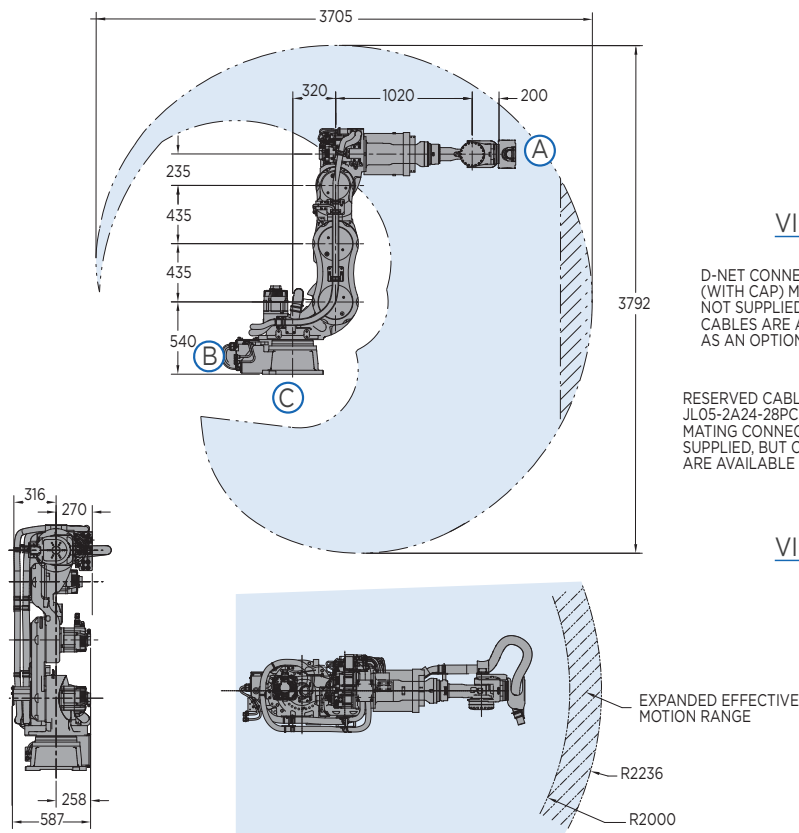
CONTROLLER

YRC1000

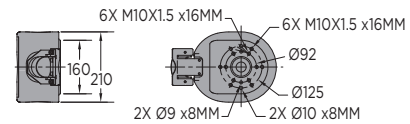


- Powerful and efficient seven-axis SP100B robot features highly flexible range of motion.
- Slim profile design allows reaching into confined spaces and close proximity placement of robots for high-density workcells and product line layout flexibility.
- Seven axes provide greater end-of-arm motion range and additional flexibility for obstacle avoidance in tight work areas.
- Wide wrist motion range reduces interference and improves application flexibility.
- Distance between the L-axis and U-axis can be changed by adjusting the angle of the E-axis, effectively creating a variable length L arm.
- Integrated spot harness improves wrist flexibility and reduces downtime.
- Servo gun and DC timer technology optimized for productivity and quality.
- Spot monitoring and waveform graphing helps check and troubleshoot welding conditions.
- Controller connectivity provides simple wiring to spot timers.
- Robot pendant application for programming Medar® and Nadex® brand timers.
- Spot harness connections
 - Connections from base to upper arm
 - DeviceNet signal and power
 - Connections from base to wrist (gun)
 - Servo motor and encoder
 - Air hose (2) 6.5 mm ID, (1) 8 mm ID
 - Water hose (4) 8 mm ID
 - Weld power (2) 22 mm², (1) 14 mm²
 - Transformer thermostat (3) 0.75 mm²
 - User I/O (9) twisted pair + (1) 0.3 mm²
- Modular robot harness design for improved diagnostics and maintenance.
- Home position data can be saved without battery connection for easy maintenance.
- The SP100B has an IP67-rated wrist and an IP54 body standard.
- Compact YRC controller utilizes the lightweight standard teach pendant with intuitive programming.

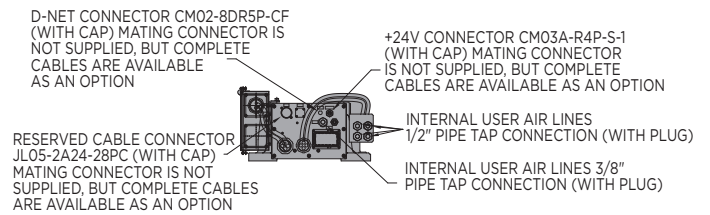
SP100B ROBOT



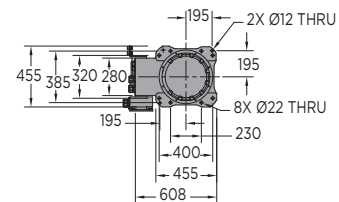
VIEW A



VIEW B



VIEW C



All dimensions are metric (mm) and for reference only. Request detailed drawings for all design/engineering requirements.

SPECIFICATIONS

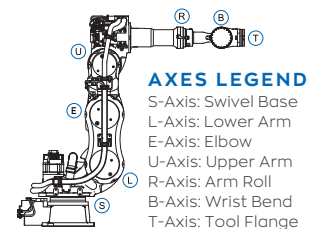
Axes	Maximum motion range	Maximum speed	Allowable moment	Allowable moment of inertia
	degrees	°/sec	N·m	kg·m ²
S	±180	140	-	-
L	+155/-45	110	-	-
E	+120/-45	110	-	-
U	+90/-70	130	-	-
R	±205*	175	696	58
B	±120*	175	696	58
T	±205*	255	294	33

* Motion range limited by spot harness
Mounting Options: Floor

Item	Unit	SP100B
Controlled axes		7
Maximum payload	kg	100
Repeatability	mm	0.04
Horizontal reach	mm	2,236
Vertical reach	mm	3,792
Weight	kg	825
Internal user I/O cable		24 conductors w/ ground
Internal user air line		(1) 3/8" connection
Power requirements		380-480 VAC
Power rating	kVA	5

OPTIONS

- Robot risers and base plates
- Extended length manipulator cables
- Wide variety of fieldbus cards
- External axes
- Functional Safety Unit (FSU)
- MotoSight™ 2D and 3D vision



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